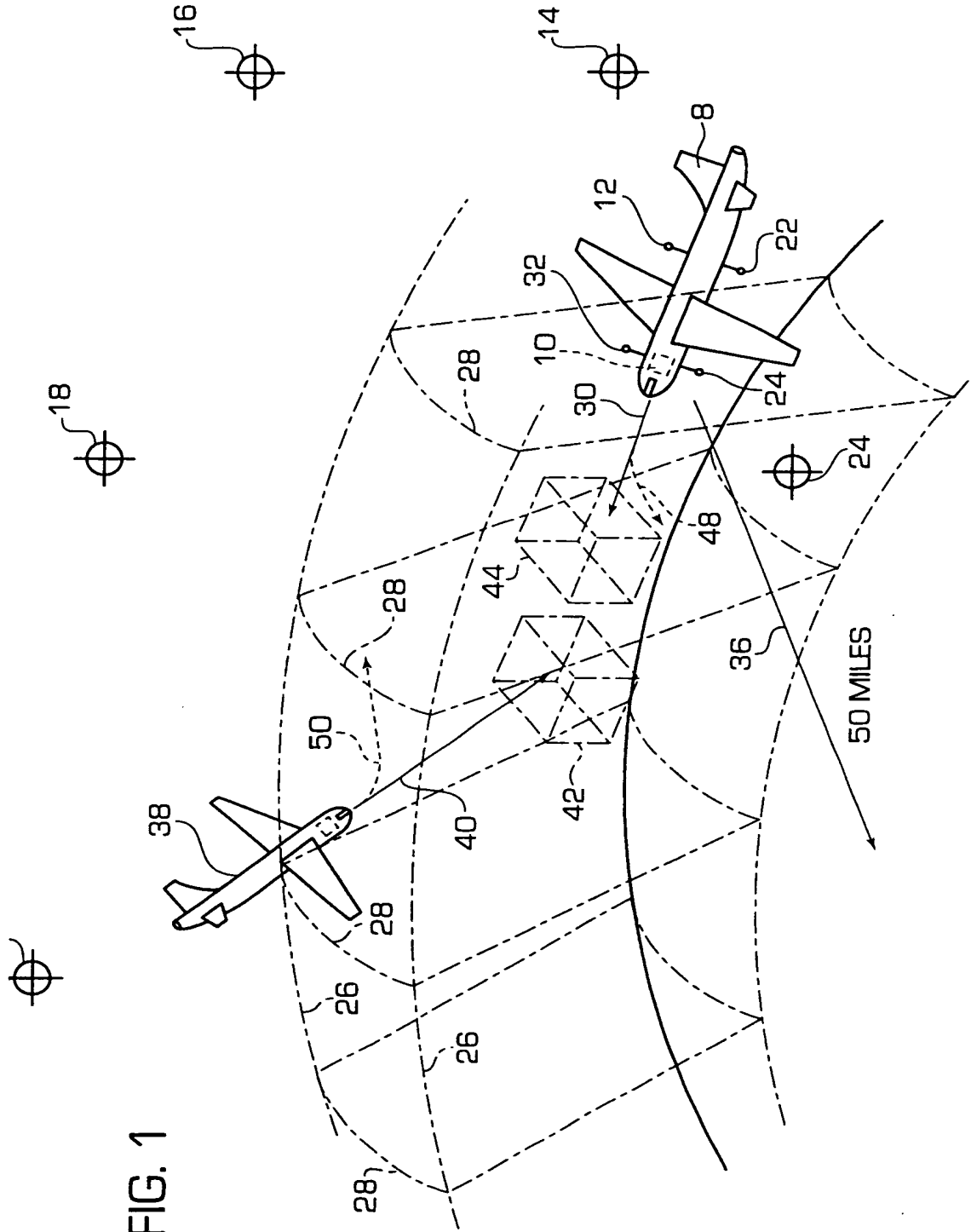


FIG. 1



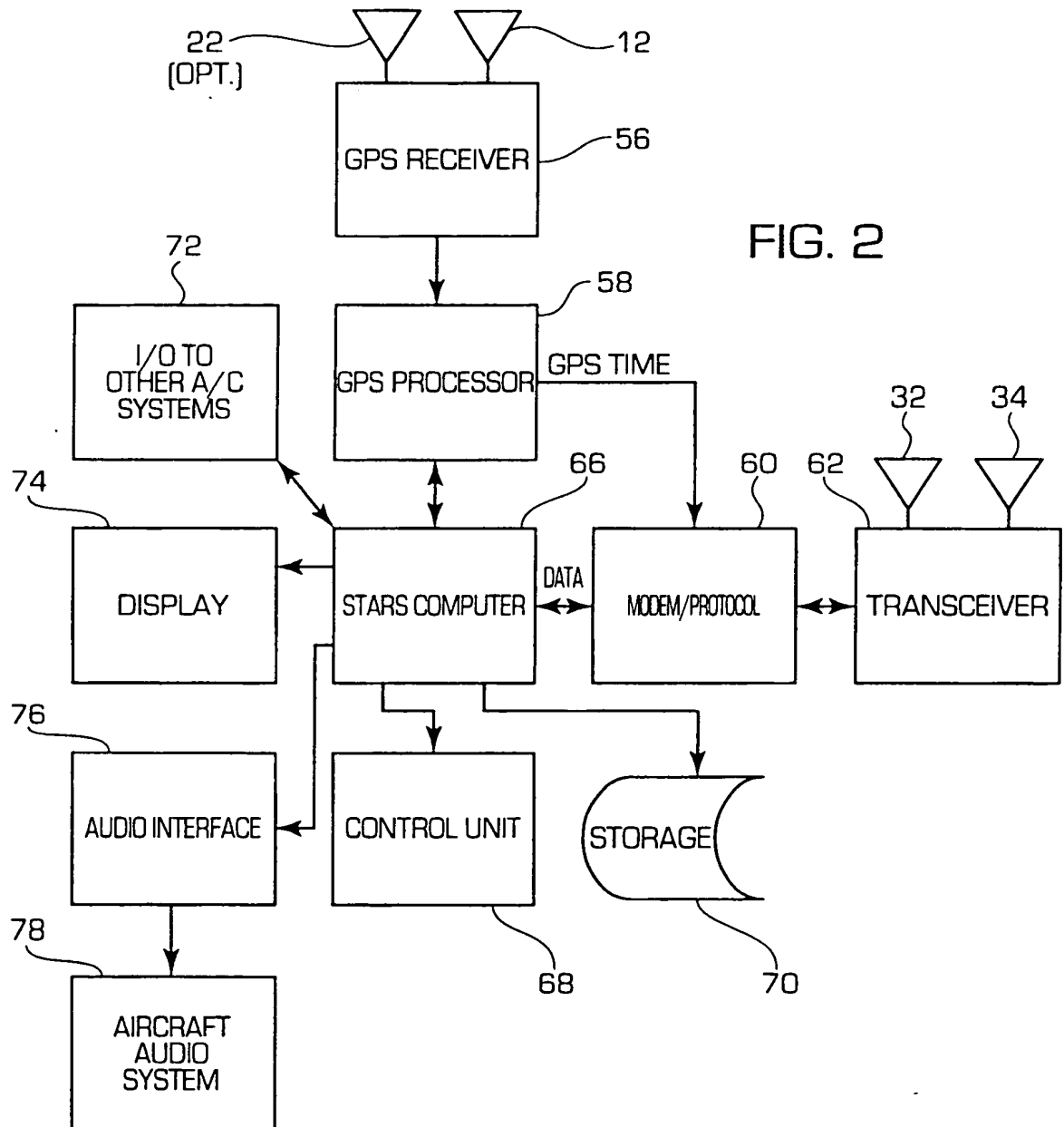


FIG. 3

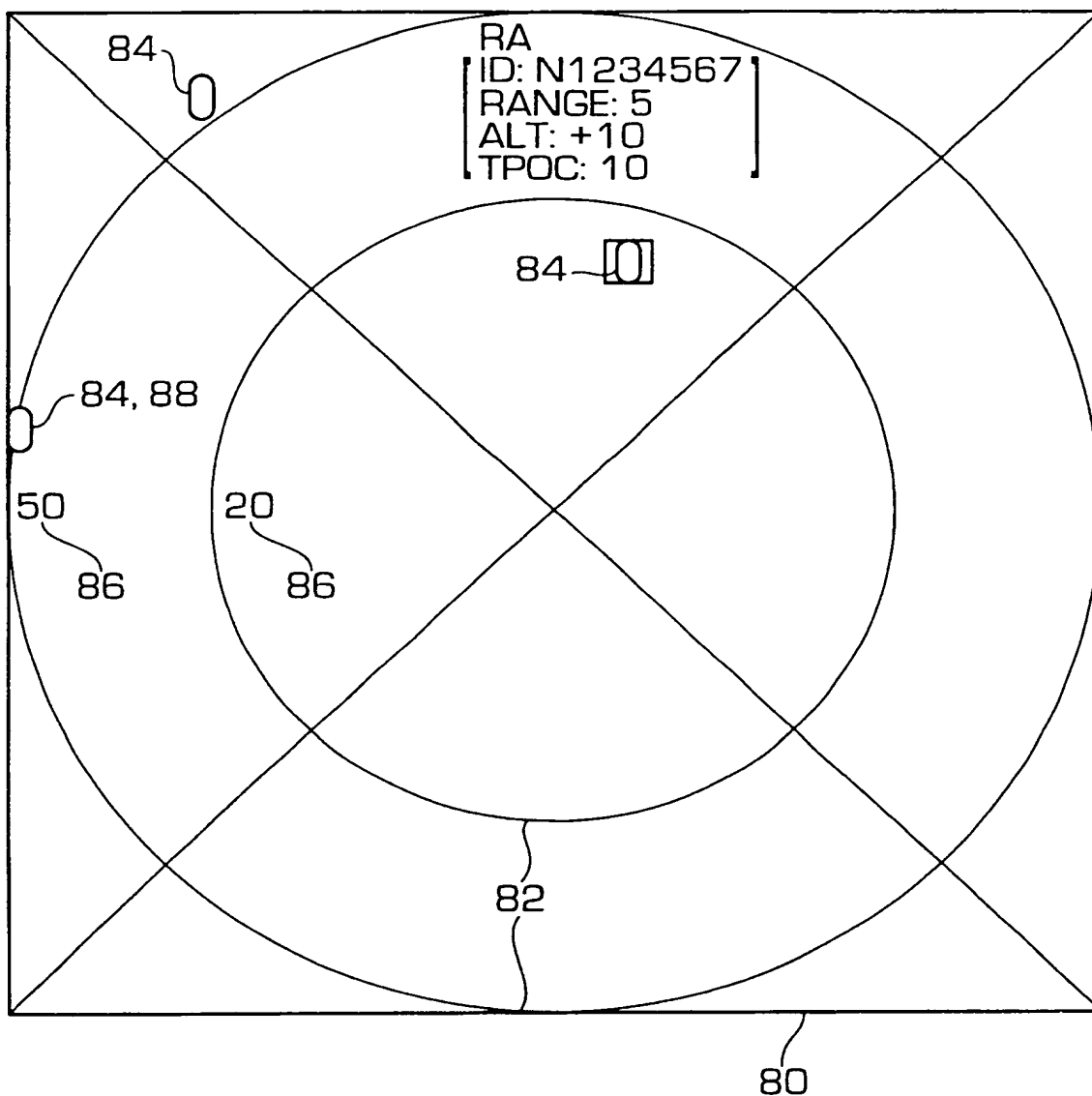
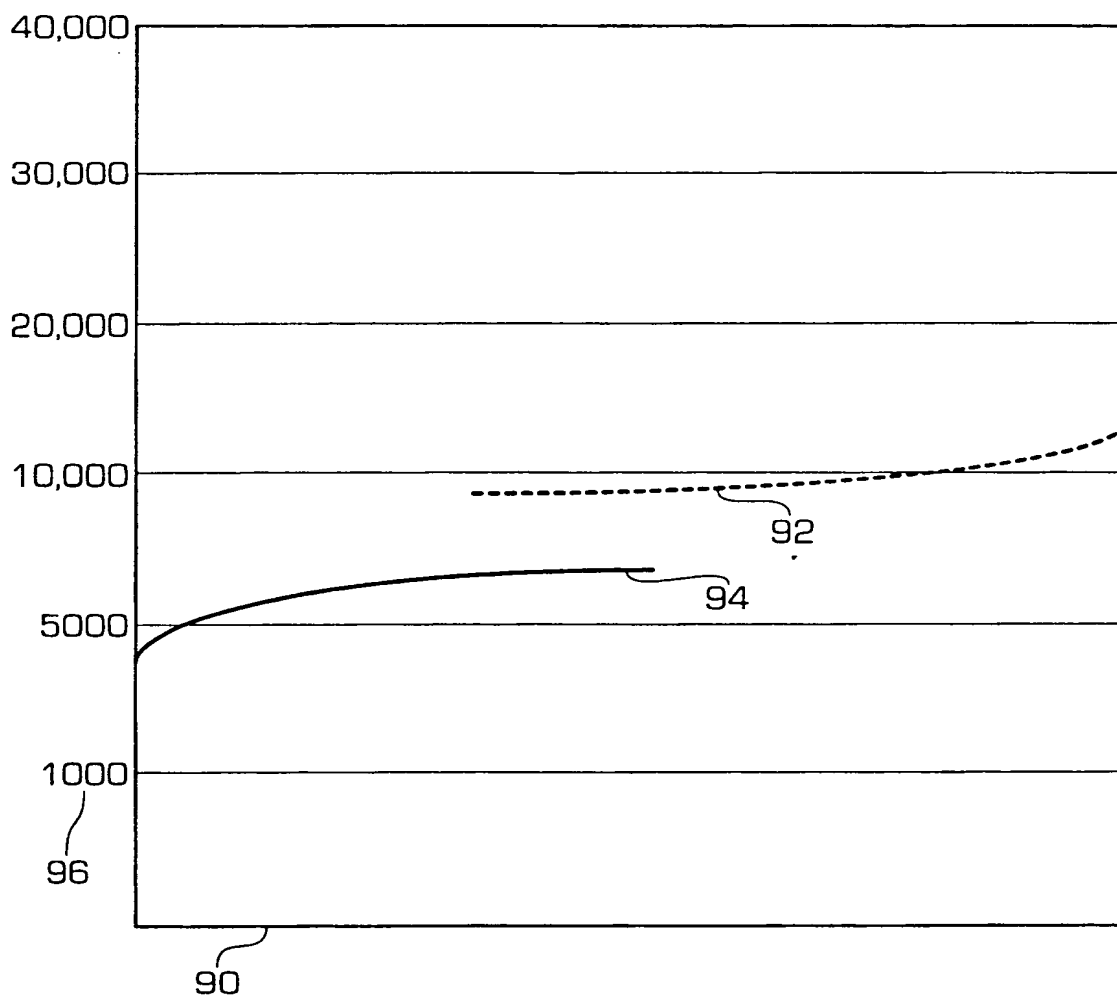


FIG. 4



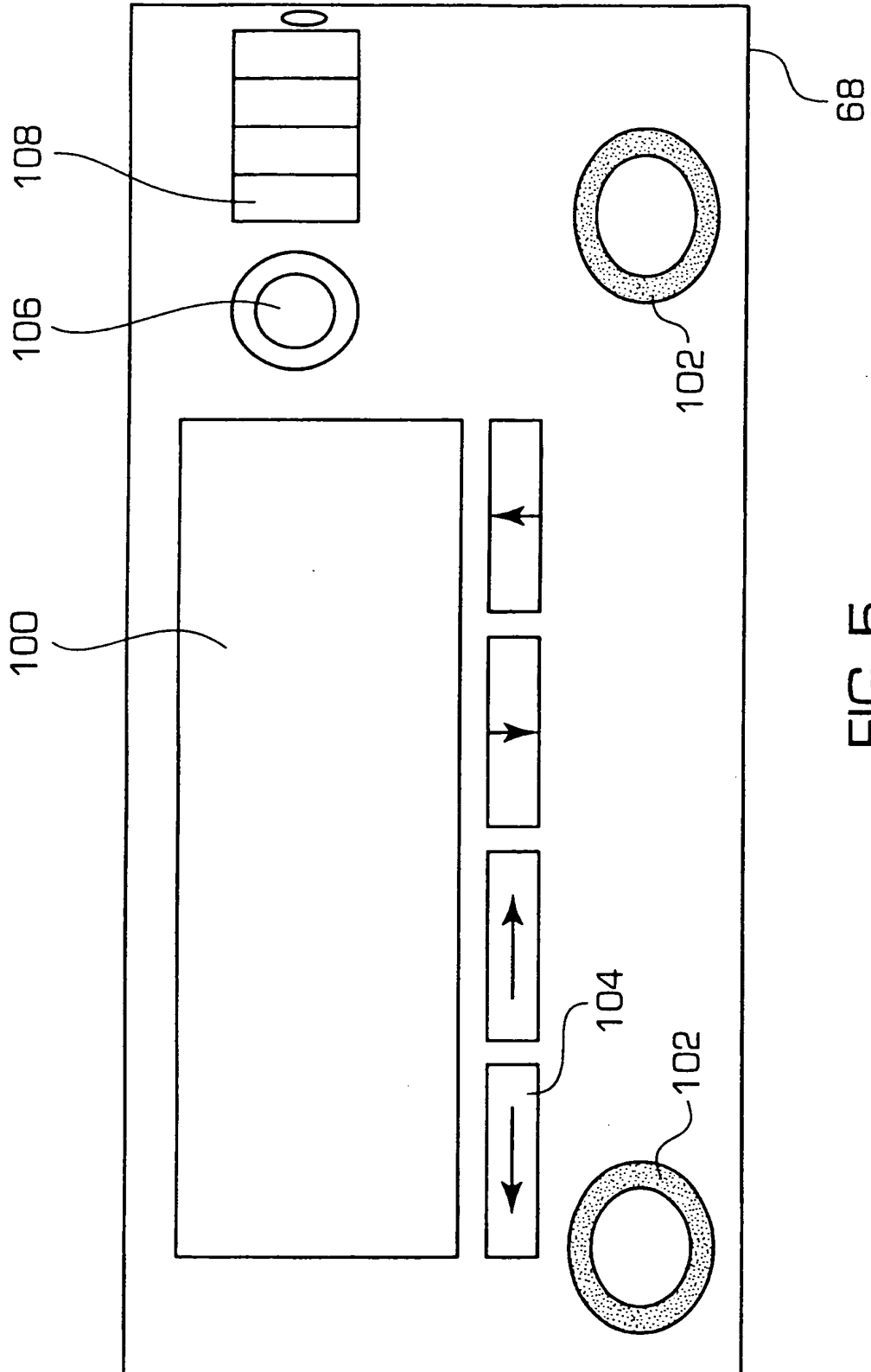
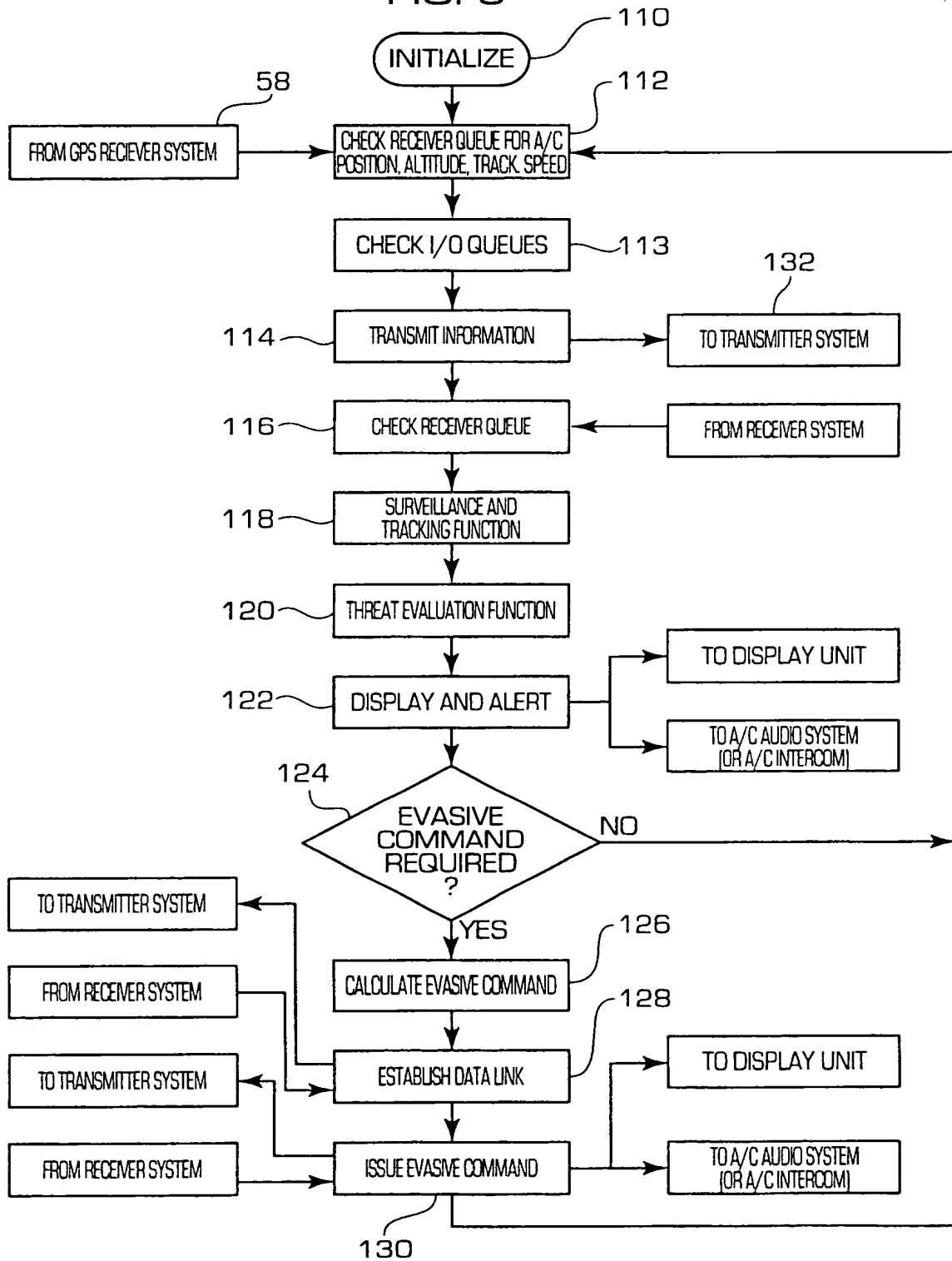


FIG. 5

FIG. 6



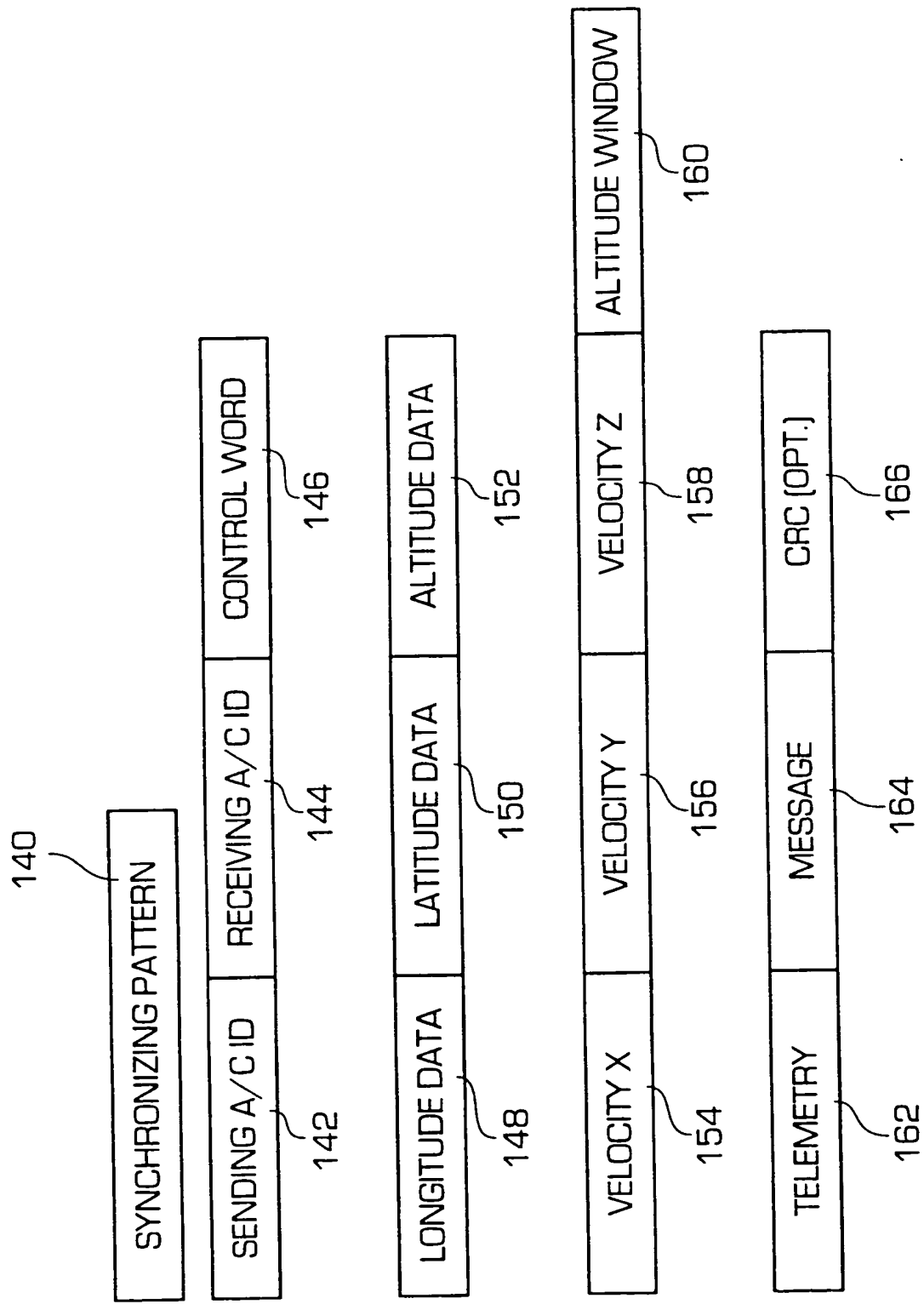


FIG. 7

FIG. 8

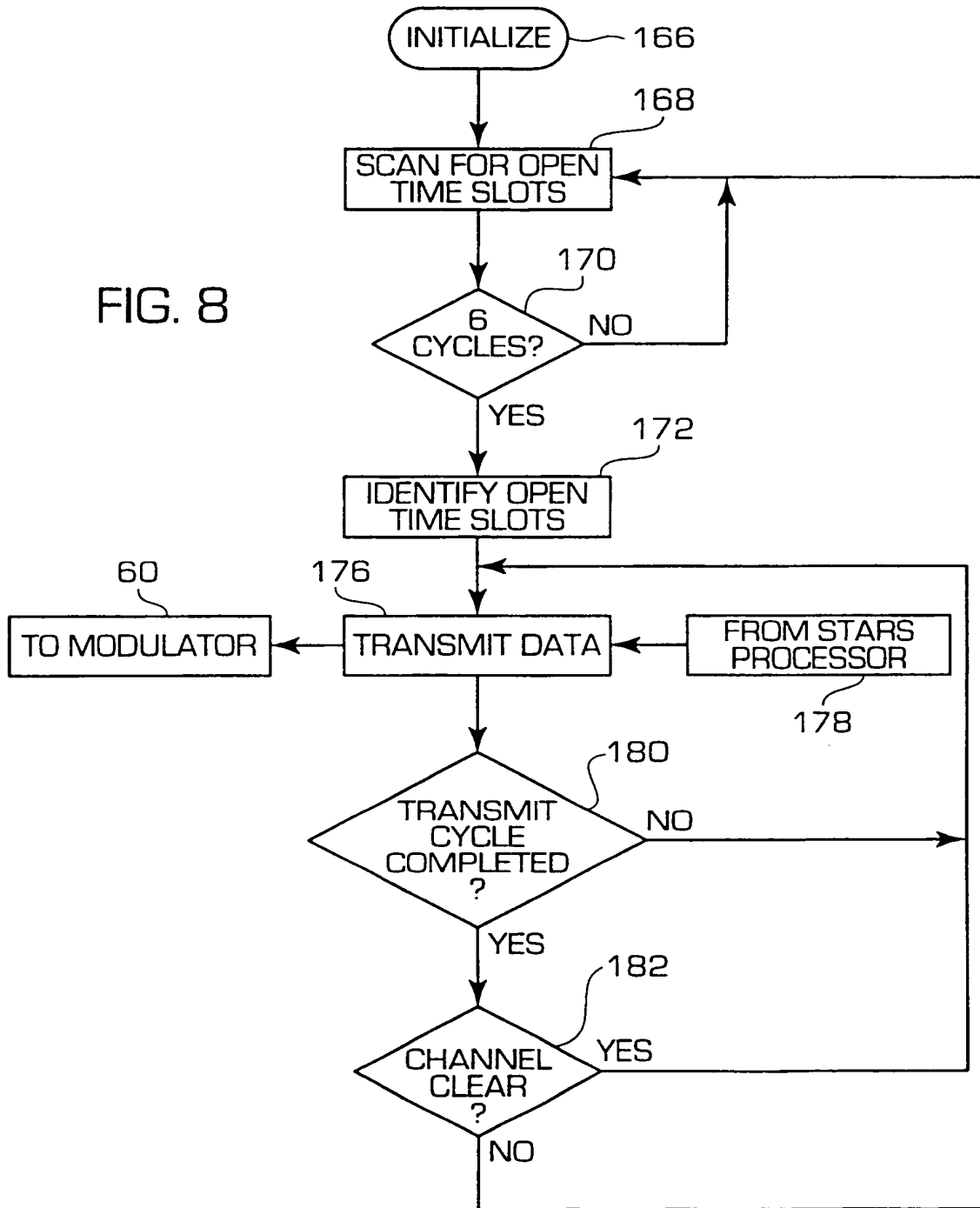




FIG. 9

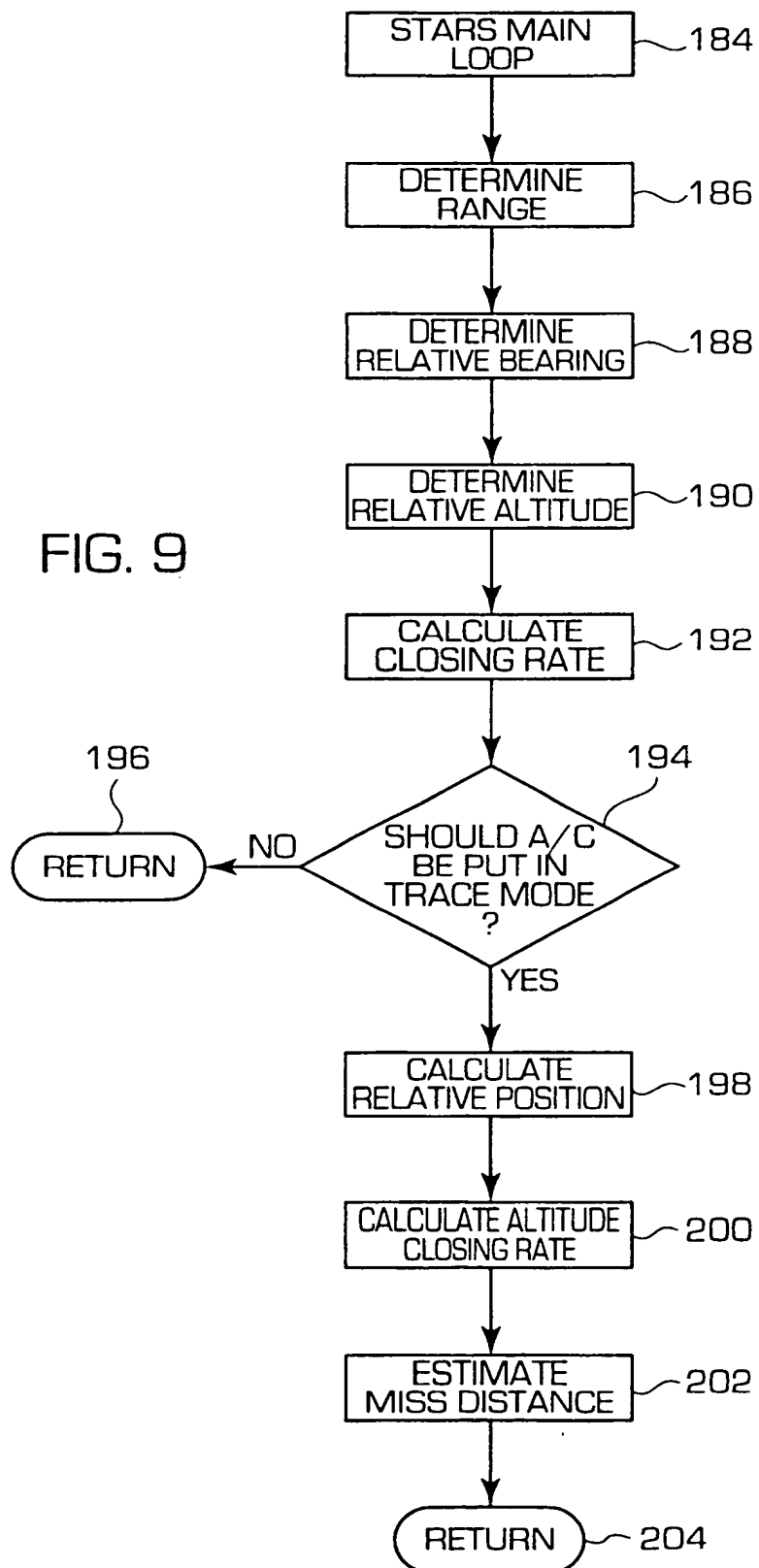
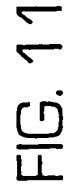


FIG. 10

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graph TD; 118[SURVEILLANCE AND TRACKING FUNCTION] --> 120[THREAT EVALUATION FUNCTION]; 120 --> 206[CATEGORIZE]; 206 --> 208[RESOLUTION ADVISORY]; 206 --> 214[NON-THREAT]; 206 --> 210[TRAFFIC ADVISORY]; 206 --> 212[PROXIMITY]; 208 --> 216((RETURN)); 214 --> 216; 210 --> 216; 212 --> 216;
```

The flowchart illustrates a process for threat evaluation and categorization. It begins with a 'SURVEILLANCE AND TRACKING FUNCTION' (118), which leads to a 'THREAT EVALUATION FUNCTION' (120). The output of the evaluation function is then processed by a 'CATEGORIZE' block (206). This block branches into four paths: 'RESOLUTION ADVISORY' (208), 'NON-THREAT' (214), 'TRAFFIC ADVISORY' (210), and 'PROXIMITY' (212). All four advisory paths converge at a 'RETURN' terminal (216).



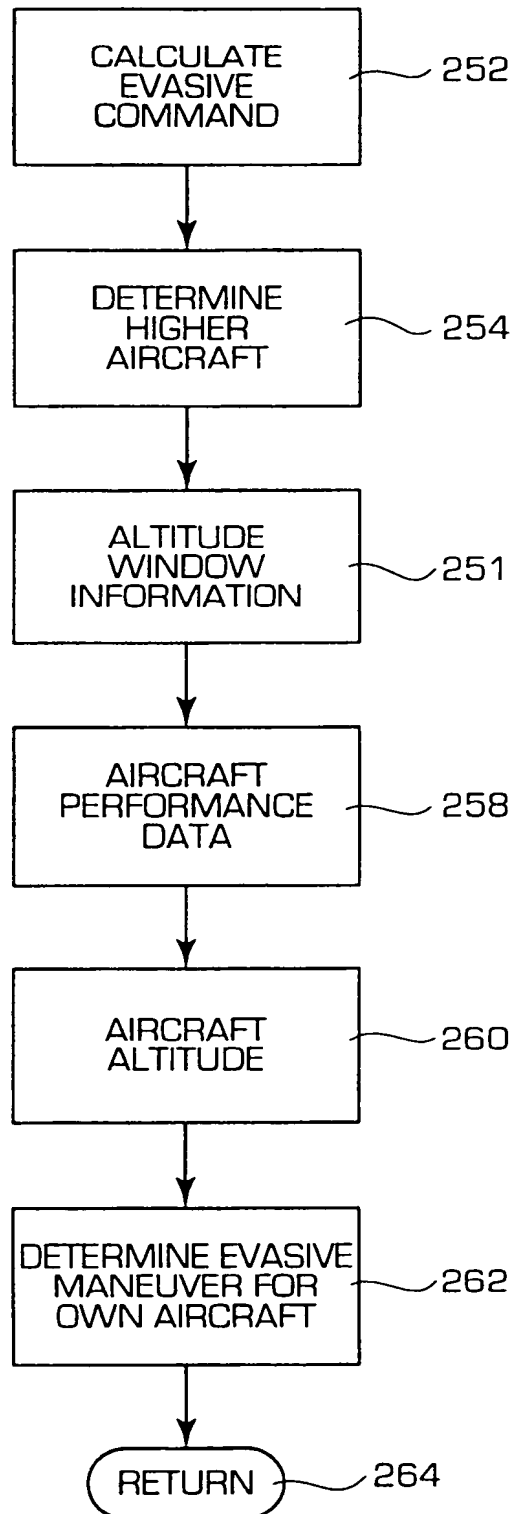


FIG. 12

FIG. 13

